

# Package: optimCheck (via r-universe)

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**Type** Package

**Title** Graphical and Numerical Checks for Mode-Finding Routines

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**Description** Tools for checking that the output of an optimization algorithm is indeed at a local mode of the objective function. This is accomplished graphically by calculating all one-dimensional "projection plots" of the objective function, i.e., varying each input variable one at a time with all other elements of the potential solution being fixed. The numerical values in these plots can be readily extracted for the purpose of automated and systematic unit-testing of optimization routines.

**URL** <https://github.com/mlsy/optimCheck>,  
<https://mlsy.github.io/optimCheck/>

**BugReports** <https://github.com/mlsy/optimCheck/issues>

**License** GPL-3

**Imports** stats, graphics

**RoxygenNote** 7.3.1

**Encoding** UTF-8

**Suggests** testthat, quantreg, mclust, knitr, rmarkdown

**VignetteBuilder** knitr

**Roxygen** list(markdown = TRUE)

**Repository** <https://mlsy.r-universe.dev>

**RemoteUrl** <https://github.com/mlsy/optimcheck>

**RemoteRef** HEAD

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optimCheck-package	<i>Graphical and numerical checks for mode-finding routines.</i>
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### Description

Tools for checking that the output of an optimization algorithm is indeed at a local mode of the objective function. This is accomplished graphically by calculating all one-dimensional "projection plots" of the objective function, i.e., varying each input variable one at a time with all other elements of the potential solution being fixed. The numerical values in these plots can be readily extracted for the purpose of automated and systematic unit-testing of optimization routines.

### Author(s)

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### See Also

Useful links:

- <https://github.com/mlysy/optimCheck>
- Report bugs at <https://github.com/mlysy/optimCheck/issues>

### Examples

```
# example: logistic regression
ilogit <- binomial()$linkinv

# generate data
p <- sample(2:10,1) # number of parameters
n <- sample(1000:2000,1) # number of observations
X <- matrix(rnorm(n*p),n,p) # design matrix
beta0 <- rnorm(p, sd = .1) # true parameter values
y <- rbinom(n, size = 1, prob = ilogit(X %*% beta0)) # response

# fit logistic regression
bhat <- coef(glm(y ~ X - 1, family = binomial))
```

```

# check convergence

# likelihood function
loglik <- function(beta, y, X) {
  sum(dbinom(y, size = 1, prob = ilogit(X %*% beta), log = TRUE))
}

# projection plots
bnames <- parse(text = paste0("beta[", 1:p, "]"))
system.time({
  oproj <- optim_proj(xsol = bhat,
                    fun = function(beta) loglik(beta, y, X),
                    xnames = bnames,
                    xlab = "Coefficient", ylab = "Loglikelihood")
})

# numerical summary
oproj # see ?summary.optproj for more information

# elementwise differences between potential and optimal solution
diff(oproj) # same as summary(oproj)$xdiff

# refit general purpose optimizer starting from bhat
# often faster than optim_proj, but less stable
system.time({
  orefit <- optim_refit(xsol = bhat,
                      fun = function(beta) loglik(beta, y, X))
})
orefit

```

---

diff.optcheck

*Elementwise difference between potential and optimal solutions.*


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## Description

Elementwise difference between potential and optimal solutions.

## Usage

```

## S3 method for class 'optcheck'
diff(x, ...)

## S3 method for class 'summary.optcheck'
diff(x, ...)

```

## Arguments

**x** Object of class `optcheck` or `summary.optcheck`, currently returned by `optim_proj()`, `optim_refit()`, or a summary of either of those calls.

**...** Further arguments to be passed to or from other methods.

**Details**

This function is simply a wrapper to `summary(x)$xdiff` and `x$xdiff`, for `optcheck` and `summary.optcheck` objects respectively.

**Value**

A two-column matrix consisting of the absolute and relative differences between the potential and optimal solutions (`xsol` and `xopt`).

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optim_proj	<i>Projection plot test.</i>
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**Description**

Given the objective function of an optimization problem and a potential solution, calculates "projection plots" along each coordinate of the solution vector, with all other coordinates being fixed at the input values.

**Usage**

```
optim_proj(
  xsol,
  fun,
  maximize = TRUE,
  xrng = 0.1,
  npts = 100,
  plot = TRUE,
  ...
)
```

**Arguments**

<code>xsol</code>	Potential solution vector of length <code>nx</code> .
<code>fun</code>	Objective function to be maximized (or minimized), with first argument the length- <code>nx</code> parameter vector over which optimization is to take place. Should return a scalar result.
<code>maximize</code>	Logical, whether a maximum or a minimum of the objective function is sought.
<code>xrng</code>	Optional specification of the range of each projection plot. Can be: (i) a $2 \times nx$ matrix giving the endpoints of the range, (ii) a scalar or vector of length <code>nx</code> , such that the range in each plot is $\theta \pm \text{xrange} * \text{abs}(\theta)$ .
<code>npts</code>	Number of points in each projection plot.
<code>plot</code>	Logical, whether or not to display the projection plots or just return their contents.
<code>...</code>	Further arguments to pass to the plot method (see <code>plot.optproj()</code> ).

**Value**

An object of class `optproj` inheriting from `optcheck` (returned invisibly if `plot = TRUE`, with elements:

`xsol` The potential solution.

`ysol` The value of `fun(xsol)`.

`maximize` Logical indicating whether the potential solution should maximize or minimize the objective function.

`xproj` An `npts × nx` matrix where each column is the x-axis of the projection plot along the given component of `theta`.

`yproj` An `npts × nx` matrix where each column is the y-axis of the corresponding projection plot.

**See Also**

`plot`, `summary`, `print`, and `diff` methods for projection plots are available; see `plot.optproj()`, `summary.optproj()`, `print.optproj()`, and `diff.optproj()`.

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`optim_refit`

*Refined optimization test.*

---

**Description**

If the potential solution is indeed a local optimum of the objective function, and if it is used to initialize a second optimization, then original and "refined" solutions ought to be close.

**Usage**

```
optim_refit(xsol, fun, maximize = TRUE, maxit = 5000, reltol = 1e-08, xopt)
```

**Arguments**

<code>xsol</code>	Potential solution vector of length <code>nx</code> .
<code>fun</code>	Objective function to be maximized (or minimized), with first argument the length- <code>nx</code> parameter vector over which optimization is to take place. Should return a scalar result.
<code>maximize</code>	Logical, whether a maximum or a minimum of the objective function is sought.
<code>maxit</code>	Maximum number of iterations for <code>stats::optim()</code> refit (see Details).
<code>reltol</code>	Relative tolerance for convergence of <code>stats::optim()</code> refit (see Details).
<code>xopt</code>	Optional refit solution calculated externally from an optimization algorithm of choice (see Details).

**Details**

By default, a so-called **refined** `optim()` (or `refit`) test is performed by running the default Nelder-Mead simplex method provided by `stats::optim()`, initialized by the potential solution `xsol`. Only a simplified interface to `stats::optim()`'s control parameters are provided here.

Alternatively, the `refit` test can be performed with any optimization algorithm of choice. This is done externally, with the refined solution passed to `optim_refit()` via the argument `xopt`.

**Value**

An object of class `optrefit` inheriting from `optcheck`, with elements:

`xsol` The potential solution.

`ysol` The value of `fun(xsol)`.

`maximize` Logical indicating whether the potential solution should maximize or minimize the objective function.

`xopt` The solution found by the general-purpose optimizer.

`yopt` The function value at the optimal solution, i.e., `fun(xopt)`.

**See Also**

`summary`, `print`, and `diff` for `optrefit` objects are available; see `summary.optrefit()`, `print.optrefit()`, and `diff.optrefit()`.

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`plot.optproj`

*Projection plots for optimization routines.*

---

**Description**

Projection plots for optimization routines.

**Usage**

```
## S3 method for class 'optproj'
plot(x, xnames, xind, equalize = FALSE, layout, xlab, ylab, ...)
```

**Arguments**

<code>x</code>	An <code>optproj</code> object, i.e., output from function <code>optim_proj()</code> .
<code>xnames</code>	Optional vector of names for the plot titles.
<code>xind</code>	Integer or logical vector of indices indicating which projections should be plotted. Defaults to all projection plots.
<code>equalize</code>	If <code>TRUE</code> , narrows the range in each projection plot such that the y-value is more or less the same at either endpoint.
<code>layout</code>	Optional vector giving the number of rows and columns in the plot layout. For <code>nx</code> plots, defaults to <code>c(nr, nc)</code> , where <code>nr = floor(nx)</code> and <code>nc = ceiling(nx/nr)</code> .
<code>xlab, ylab</code>	Outer x-axis and y-axis labels.
<code>...</code>	Further arguments to be passed to or from other methods.

**Value**

A grid of projection plots, with vertical lines at the potential solution.

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print.optcheck	<i>Print method for optcheck and summary.optcheck objects.</i>
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**Description**

Print method for optcheck and summary.optcheck objects.

**Usage**

```
## S3 method for class 'optcheck'
print(x, digits = max(3L, getOption("digits") - 3L), n = 5L, ...)

## S3 method for class 'summary.optcheck'
print(x, digits = max(3L, getOption("digits") - 3L), n = 5L, ...)
```

**Arguments**

x	Object of class optcheck or summary.optcheck, currently returned by <a href="#">optim_proj()</a> , <a href="#">optim_refit()</a> , or a summary of either of those calls.
digits	Number of digits to display.
n	Number of elements of solution vector to display (see <a href="#">Details</a> ).
...	Further arguments to be passed to or from other methods.

**Details**

The print methods for optcheck and summary.optcheck objects both display three-column matrix, consisting of the potential solution (xsol), the absolute difference between it and the optimal solution (xopt) return by either [optim\\_proj\(\)](#) and [optim\\_refit\(\)](#), and the relative difference ( $R = (xopt - xsol)/|xsol|$ ). Only the elements corresponding to the top-n relative differences are displayed.

**Value**

Invisibly x itself.

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summary.optproj      *summary method for projection plots.*

---

### Description

summary method for projection plots.

### Usage

```
## S3 method for class 'optproj'
summary(object, xnames, ...)
```

### Arguments

object	An optproj object, i.e., output from the function <code>optim_proj()</code> .
xnames	Optional vector of names for the elements of the potential solution.
...	Further arguments to be passed to or from other methods.

### Details

The print methods for `summary.optproj` and `optproj` objects themselves both return a three-column matrix, consisting of the potential solution (`xsol`), the optimal solution in each projection plot (`xopt`), and the relative difference between the two ( $R = (xopt - xsol) / |xsol|$ ).

### Value

An object of class `summary.optproj` inheriting from `summary.optcheck`, with elements:

`xsol` The potential solution vector.

`ysol` The value of the objective function at `xsol`.

`maximize` Logical indicating whether the potential solution should maximize or minimize the objective function.

`xopt` A vector containing the argmax/argmin in each projection plot.

`yopt` A vector containing the max/min in each projection plot.

`xdiff` A two-column matrix containing the differences between `xsol` and `xopt`. The first column is the absolute difference  $D = xopt - xsol$ , the second is the relative difference  $R = D / |xsol|$ .

`ydiff` Same thing, but between `ysol` and `yopt`.

### See Also

`print.summary.optproj()` for print method.



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summary.optrefit	summary method for optrefit objects.
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**Description**

summary method for optrefit objects.

**Usage**

```
## S3 method for class 'optrefit'
summary(object, xnames, ...)
```

**Arguments**

object	An optrefit object, i.e., output from the function <a href="#">optim_refit()</a> .
xnames	Optional vector of names for the elements of the potential solution.
...	Further arguments to be passed to or from other methods.

**Value**

An object of class `summary.optrefit` inheriting from `summary.optcheck`, with elements:

`xsol` The potential solution vector.

`ysol` The value of the objective function at `xsol`.

`maximize` Logical indicating whether the potential solution should maximize or minimize the objective function.

`xopt` A vector containing the argmax/argmin in each projection plot.

`yopt` The scalar value of the max/min found by `optim_refit`.

`xdiff` A two-column matrix containing the differences between `xsol` and `xopt`. The first column is the absolute difference  $D = xopt - xsol$ , the second is the relative difference  $R = D/|xsol|$ .

`ydiff` A length-two vector containing the absolute and relative difference between `ysol` and `yopt`.

**See Also**

[print.summary.optcheck\(\)](#) for print method.

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